

Design of 5 kW Radial Type Centrifugal Blower (Casing)

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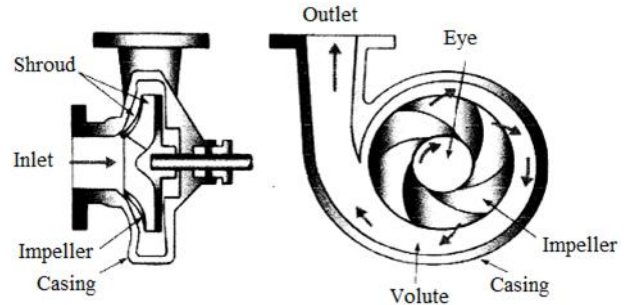
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Abstract- There exist few design methodologies for centrifugal blowers and fans in the literature. However unified design methodology particularly for radial tipped centrifugal blowers and fans is not easily traceable in the literature available. In this research paper is attempted to design a single stage radial type centrifugal blower volute casing design for used in required industrial area. In this thesis, the bower volute casing is designed to provide low volume, high pressure air for cooling, ventilating and exhaust system that handle dust, materials or corrosive fumes. This centrifugal blower can produce 20 in of w.g (0.7396 psi) and 2121 ft³/min (60 m³/min; of air at 60 °F and design speed 3450 rpm. In this research, the blower is designed air horsepower is 7 a.hp (5.2 kW) and the brake horsepower is 10 b.hp (7.5 kW). After choosing the design data from catalogue, the results of impeller inlet and outlet dimensions and vane angle could be obtained. This volute casing using Tabular Integration Method.

Indexed Terms- Centrifugal blowers, fans, Design, Volute, power, Tabular Integration.

I. INTRODUCTION

Air or gas enter the impeller axially through the inlet nozzle which provides light acceleration to the air before its entry to the impeller. The action of the impeller swings the gas from a smaller to a larger radius and delivers the gas at a high pressure and velocity to the casing. The centrifugal energy also contributes to the stage pressure rise. The flow from the impeller blades is collected by a spirally shaped casing known as scroll or volute. It delivers the air to the exit of the blower.



II. FLOW OUTLET FROM IMPELLER

The flow direction of the liquid at the outlet of the impeller can be:

- 1) Radial (perpendicular to inlet flow direction)
- 2) Mixed
- 3) Axial (parallel to inlet flow direction).

The flow outlet is determined by an important parameter called as the specific speed of the pump. As the specific speed of a pump design increases, it becomes necessary to change the construction of the impeller from a radial type to an axial type. Generally, it can be said that for low specific speeds (low flows and high heads) radial impellers are used whereas for high specific speeds (high flows and low heads) axial (propeller) impellers are used. The shape of impellers according to their specific speed as shown in Fig. 2.

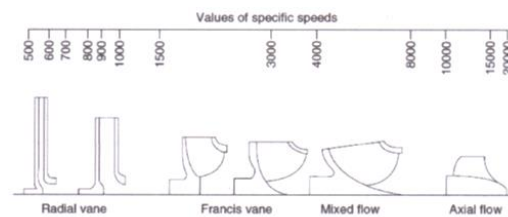


Fig. 2. Shape of Impellers According to their Specific Speed

III. DIFFUSERS AND VOLUTES

Static pressure is recovered from the kinetic energy of the flow at the impeller exit by diffusing the flow in a vane less or vaned diffuser. The spiral casing as a collector of flow from the impeller or the diffuser is an essential part of the centrifugal blower.

The provision of a vaned diffuser in blower can give a slightly higher efficiency than a blower with only a volute casing, for a majority of centrifugal blower, the higher cost and size that result by employing a diffuser outweigh its advantages. Therefore most of the single stage centrifugal blower impellers directly into the volute casing. Some static pressure recovery can also occur in a volute casing.

There is a small vaneless space between the impeller exit and the volute base circle. Volute can be designed for constants pressures or constant average velocity. The cross-section of the volute passage may be square, rectangular, circular or trapezoidal. The fabrication of a rectangular volute from sheet metal is simple; other shapes can be cast. [4]

IV. DESIGN PROCEDURE OF RADIAL TYPE CENTRIFUGAL BLOWER (IMPELLER)

This research work is based on an industrial requirement for Twin city Blower Company, Aerovent. Radial blades have lower unit blade stress for a given diameter and rotational speed hence lighter in weight. There is equal energy conversion in impeller and diffuser so it gives high-pressure ratio with good efficiency [9, 20]. Looking to these realization and facts radial blade fan is selected for this study. The input parameters for the design of radial tipped centrifugal blower are as following,

- Flow Discharge $Q = 2121 \text{ ft}^3/\text{min}$
- Static Suction Pressure = 14.7 psi (absolute)
- Static Delivery Pressure = 0.7396 psi (gauge)
- Static Pressure Gradient $\Delta P_s = 981.2 \text{ Pa}$
- Speed of impeller rotation $N = 3450 \text{ rpm}$
- Air Density = 1.165 kg/m^3
- Outlet Blade Angle $\beta_2 = 90^\circ$
- Suction Temperature $T_s = 60^\circ\text{F} = (60 + 460) = 520^\circ\text{R}$
- Atmospheric Pressure $P_{\text{atm}} = 1.01325 \times 10^5 \text{ Pa}$
- Atmospheric Temperature $T_{\text{atm}} = 30^\circ\text{C} = 303^\circ\text{K}$

These parameters are kept identical for each design methodology prescribed here in.

V. DESIGN OF VOLUTE CASING

For majority of centrifugal blowers, the higher cost and size that resulted by employing diffuser, overweigh its advantage. So most of single stage centrifugal impeller discharges directly into the volute casing, where some static pressure recovery can also occur.

Two most widely used methods of volute design areas;

1. Free vortex design.
2. Constant mean velocity design.

The purpose of the volutes as outline as outlined previously is to convert the velocity head of the gas leaving the impeller as efficiently as possible.

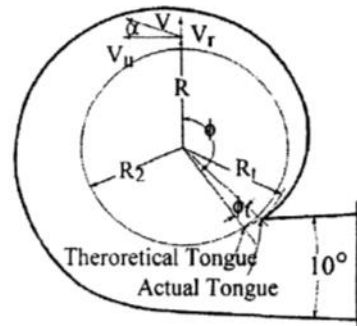


Figure 3. Elevation of Volute

The gas in the volute has very nearly the spiral flow in $RVR = C = \text{a constant}$, where C is determined from the relationship $R^2Vu^2 = C$ for a given stage.

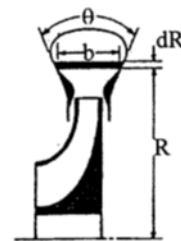


Fig.4. Section through Volute

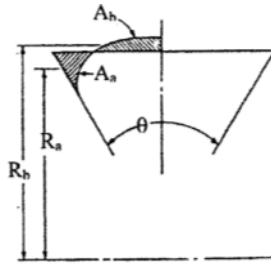


Fig.5. Volute Passage Cross Section

It may be assumed that the flow from the impeller is uniform about its periphery, so the flow past any section of the volute is $\phi/360$ of the total, where e is the angle in degrees measured from the theoretical tongue of the volute as shown in Fig. 3.

In determining the cross-sectional area of the volute at any point, the problem consists in finding the area of the section that will pass the volume $\phi/360$ with a velocity $V_u=C/R$ it should be noted that the volute of Q used is that of delivered flow. It does not include the leakage flow which has now split off from the total impeller flow and returned to the suction through the wearing rings.

If friction is neglected, the flow through the differential section shown in Fig. 4. is

$$dQ_\phi = dAV_u = b dR V_u$$

But $V_u = C/R$, here $dQ_\phi = b dR C/R$, and the total flow past the section becomes

$$Q_\phi = \int_{R_2}^{R_\phi} dQ = C \int_{R_2}^{R_\phi} b \frac{dR}{R}$$

Where, R_ϕ is the outer radius of a section at ϕ from the theoretical tongue.

Substituting for dQ_ϕ the term $\phi Q/360$ there results

$$\phi = \frac{360 C}{Q} \int_{R_2}^{R_\phi} b \frac{dR}{R} = \frac{360 R_2 V_{u2}}{Q} \int_{R_2}^{R_\phi} b \frac{dR}{R}$$

After the shape of the side walls of the volute has been decided upon, the integral can best be solved by tabular integration as illustrated in the next section.

The shape of the volute is generally similar to that shown on Fig.4. The maximum total angle θ between the sides is usually about 60. If made greater the water

is unable to follow the sides and turbulence and inefficiency result. Volute with smaller θ angles and larger radii give better results, but then the casing diameter and weight of the pump are increased unduly. If the discharge angle from the impeller α_2 is small, a larger angle between the sides may be used since the flow is then more nearly tangential. In order to simplify the calculations it may be assumed that the top of the volute is parallel to the shaft axis. After the areas have been found on this basis, the top wall of the volute may be made of any desired shape by substituting equivalent area for the original ones. Since $R V_w$ is a constant and $V_w = dQ/A$ at each section, it may be seen that dQR/A must be constant also, Hence $R_a dQ/A_a = R_b Q/A_b$ or $A_a/R_a = A_b/R_b$ and $A_b = A_a R_b/R_a$ where R_a and R_b are the distance from the shaft axis to the respective centers of gravity of the corresponding area as shown in Fig. 5.

These corrections may, in most cases, be neglected since the ratio R_b/R_a is usually very near unity and inherent casting inaccuracies destroy extreme refinements in calculation. It should also be remembered that the above calculation are based upon frictionless flow. Since the actual velocity is lower, the areas must be arbitrarily increased to care for this. This arbitrary increase in area may be much greater than the correction for the change of shape of passage.

To avoid shock losses the tongue angle should be made the same as the absolute outlet angle α_2 of the water leaving the impeller. The radius R_t at which the tongue starts should be 5 to 10 percent greater than the outside radius of the impeller to avoid turbulence and noisiness and to give the velocities of the water leaving the impeller a chance to equalize before coming into contact with the tongue.

The zero point of the volute or the point from which the angle ϕ is measured may be found by assuming that the flow follows a logarithmic spiral. The equation of a logarithmic spiral is:

$$R = R_2 e^{\tan \alpha_2 \phi}$$

Where, ϕ is the angle measured in radians

α_2 is the constant angle of the spiral or the angle at which the water leaves the impeller

e is the base of natural logarithms=2.718

$$\text{Log}_{10}R = \text{Log}_{10}R_2 + \tan\alpha'_2 \frac{\pi\theta^\circ}{180} \text{Log}_{10}718$$

Hence,

$$\phi_t = \frac{132 \text{Log}_{10} \frac{R}{R_2}}{\tan \alpha_2}$$

For the tongue radius $R=R_t$ and

$$\phi_t = \frac{132 \text{Log}_{10} \frac{R_t}{R_2}}{\tan \alpha'_2}$$

In the passage between the volute and discharge flange further conversion of velocity into pressure may take place, especially with high head pumps by making it divergent. In order to avoid turbulence the total divergence in this passage should not exceed 10°. They velocity here should never be greater than the minimum velocity the volute, otherwise some of the pressure energy would be reconverted to velocity. [2]

Table 1. Result Data of Impeller

Name	Symbol	Result
Shaft Diameter	D_s	1.5 in
Hub Diameter	D_H	2.5 in
Eye diameter	D_0	8 in
Eye velocity	V_0	100 ft/sec
Flow through eye	Q_0	35.5 ft ³ /sec
Vane inlet diameter	D_1	8.25 in
Velocity at vane inlet	V_1	100 ft/sec
Impeller inlet width	b_1	2.5 in
Inlet vane angle	β_1	38°
Inlet vane thickness	ϵ_1	0.85 in
Number of vanes	z	15
Inlet tip speed	U_1	124.191 ft/sec
Outside dia. of impeller	D_2	18 in
Impeller outlet tip speed	U_2	270.962 ft/sec
Tangential component of outlet vel;	V_{u2}	214.212 ft/sec
Impeller outlet width	b_2	1.5 in
Outlet vane thickness	ϵ_2	0.93 in
Vane outlet angle	β_2	90°
Absolute vel;	V'_2	223.284 ft/sec

Absolute outlet angle:	α'_2	16°
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VI. TABULAR INTEGRATION METHOD FOR CASING DESIGN

The preliminary shape of the volute section will be taken as a trapezoid with the side walls at 30° angle with the radial lines ($\theta = 60^\circ$) and a base width of 2.5 in at the impeller outlet D_2 . This base width is found by adding to the outlet width b_2 twice the shroud width and twice the axial clearance. The width of the volute at any point may be scaled from a layout or calculated from the equation $b = b_3 + 2x \tan(\theta/2)$, where x is the distance between any radius R and the impeller rim radius R_2 .

A. The base width:

$$b_3 = b_2 + (2 \times \text{shroud width}) + (2 \times \text{axial clearance})$$

$$= 1.5 + (2 \times 1/4) + (2 \times 1/4) = 2.5 \text{ in}$$

If angle between sides is $\theta = 60^\circ$, the width of volute at any point will become

$$b = b_3 + 2 \times \tan(60/2)$$

$$b = 2.5 + 2 \times \tan 30^\circ$$

The tongue radius R_t is made about 10 percent more than the tip radius R_2 .

$$R_t = 1.1 \times 9 = 9.9 \text{ in}$$

The tongue angle ϕ_t may be found from following eqn;

$$\phi_t = \frac{132 \text{Log}_{10} \frac{R}{R_2}}{\tan \alpha_2}$$

For the tongue radius $R=R_t$ and

$$\phi_t = \frac{132 \text{Log}_{10} \frac{R_t}{R_2}}{\tan \alpha'_2}$$

$$\text{Log}_{10} \frac{R_t}{R_2} = \log_{10} 1.1 = 0.0414$$

$$\alpha'_2 = 16^\circ$$

$$\tan \alpha'_2 = 16^\circ$$

The volute is designed by determining the angle ϕ° measured from an assumed radial line by tabular integration.

$$\phi^\circ = \frac{360 R_2 V_{u2}}{Q_2} \int_{R_2}^{R\theta} b \frac{dR}{R_{ave}} = 130.558 \int_{R_2}^{R\theta} b \frac{dR}{R_{ave}}$$

$$R_{ave} = R + \frac{\Delta R}{2}$$

$$b_{ave} = b_3 + 2(R_{ave} - R_2) \tan \frac{60}{2}$$

$$\Delta A = b_{ave} \times \Delta R$$

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